

$$\vec{F} = \frac{Qq}{r^2} \hat{r} \quad \phi = - \int_{\infty}^r E \cdot dr$$

$$\vec{E} = \frac{Q}{r^2} \hat{r} \quad -\nabla \phi(r) = -\frac{d}{dr}(\phi) = \vec{E}_{(r)}$$

$$U = \int_0^{\infty} E_{(r)}^2 \cdot dv = Q\phi = Q^2 \frac{1}{C} = \phi^2 C$$

$$\rho \rightarrow \vec{E} \quad \vec{E}_{(r)} = \frac{1}{r^j} \int r^j \cdot \rho_{(r)} \cdot dr$$

$$\vec{E} \rightarrow \rho \quad \rho_{(r)} = \frac{1}{r^j} \frac{d(r^j \cdot \vec{E}_{(r)})}{dr} = \vec{\nabla} \cdot \vec{E}_{(r)}$$

$$\Delta E = \sigma \quad \sigma \cdot R^2 = Q_{tot}$$

$$C_{par} = \Sigma C_i = \int dC \quad C_{sphere} = R \quad C = \frac{Q}{V}$$

$$\frac{1}{C_{ser}} = \Sigma \frac{1}{C_i} = \int \frac{1}{dC} \quad C_{peel} = \frac{R^2}{\Delta} = C_{surface}$$

$$E_{new} = \frac{1}{\epsilon} E_{old} \quad \phi_{new} = \frac{1}{\epsilon_{(\mp)}} \phi_{old} \quad C_{new} = \epsilon_{(\mp)} \cdot C_{old}$$

$$\lambda = \sigma \cdot 2\pi R = \rho \cdot \pi R^2$$

sphere *cylinder* *surface*

$$\vec{E}_{(r)} \quad \frac{Q}{r^2}, \frac{Q}{R^3} r \quad \frac{\lambda}{r}, \lambda r \quad \sigma$$

$$V_{(r)} \quad \frac{Q}{r} \quad \lambda \cdot \ln(r) \quad \sigma \cdot y$$

אלקטרוסטטיקה

משוואות הבסיס

$$\vec{E}_{(z,R)} \hat{z} = Q \frac{z}{(z^2 + R^2)^{\frac{3}{2}}} \hat{z} \quad \text{ring} \quad \vec{E}_{(z,R)} \hat{z} = \frac{Q}{R^2} \cdot \left(1 - \frac{z}{\sqrt{z^2 + R^2}}\right) \quad \text{disk} \quad \Phi_E = \oint_S \vec{E} \cdot ds = Q_{in} \quad \text{Gauss's law}$$

אלקטרוסטטיקה
 בקואורדינטות שונות

sphere

cylinder

plane

$$\Sigma \vec{E}_{(r)}$$

$$\frac{Q}{r^2}, \frac{VR}{r^2}$$

$$\frac{\lambda}{\rho}, \frac{1}{\ln(\frac{b}{a})} \frac{V}{\rho}$$

$$\sigma, \frac{V}{h}$$

$$\phi_{(r)}$$

$$\frac{Q}{r} +$$

$$\lambda \cdot \ln(\rho) +$$

$$\sigma \cdot y +$$

$$(\epsilon_{\neq}) \cdot C$$

$$\frac{R^2}{d}$$

$$\frac{l}{\ln \frac{b}{a}}$$

$$\frac{S}{d}$$

$$\vec{\nabla} \cdot \vec{E}_{(r)}$$

$$\frac{1}{r^2} \frac{d}{dr} (r^2 E)$$

$$\frac{1}{r} \frac{d}{dr} (r E)$$

$$\frac{d}{dr} (E)$$

$$C = \frac{Q}{V} \quad C_{plane} = \frac{S}{H} \quad 1 < \epsilon < \infty \quad \Delta E = \sigma = \frac{Q_0}{S} \frac{1}{\epsilon} = \frac{Q_0}{S} - \frac{Q_0}{S} \left(1 - \frac{1}{\epsilon}\right)$$

אלקטרוסטטיקה
קבל כדורי עם דיאלקט

$$Q_0, \epsilon(\neq)$$

$$V_0, \epsilon(\neq)$$

$$Q_0, \epsilon(r)$$

$$V_0, \epsilon(r)$$

$$-\nabla \phi(r) = \vec{E}(r)$$

$$\frac{Q_0}{S} \frac{1}{\epsilon}$$

$$\frac{V_0}{H} \frac{1}{\epsilon}$$

$$\frac{Q_0}{S} \frac{1}{\epsilon(r)}$$

$$\frac{CV_0}{S} \frac{1}{\epsilon(r)}$$

$$-\int \vec{E} \cdot d\vec{l} = \phi(r)$$

$$\frac{Q_0}{S} y \frac{1}{\epsilon}$$

$$\frac{V_0}{H} y \frac{1}{\epsilon}$$

$$\frac{Q_0}{S} \int \frac{1}{\epsilon(r)}$$

$$\frac{CV_0}{S} \int \frac{1}{\epsilon(r)}$$

$$Q_0(\text{free} - [\text{bound}])$$

$$Q$$

$$Q_0 \left(1 - \left[1 - \frac{1}{\epsilon}\right]\right)$$

$$\frac{V_0}{H} S \epsilon \left(1 - \left[1 - \frac{1}{\epsilon}\right]\right)$$

$$Q_0 \left(1 - \left[1 - \frac{1}{\epsilon(r=0)}\right]\right)$$

$$CV_0 \left(1 - \left[1 - \frac{1}{\epsilon(r=0)}\right]\right)$$

$$C$$

$$\frac{S}{H} \epsilon$$

$$\frac{S}{H} \epsilon$$

$$\frac{S}{H} \int \epsilon(r)$$

$$\frac{S}{H} \int \epsilon(r)$$

$$I = \frac{dQ}{dt} \quad VI = V \frac{dQ}{dt} = P_{[watt]}$$

$$\frac{V}{R} = I$$

$$\frac{E}{\rho_R} = J$$

$$\vec{J} = \frac{\vec{I}}{ds}, \int \vec{J} \cdot ds = \vec{I}$$

$$\vec{K} = \frac{\vec{I}}{dl}, \int \vec{K} \cdot dl = \vec{I}$$

אלקטרו דינמיקה

$$\rho_R = \frac{1}{\sigma_R}$$

$$\text{series} \Rightarrow R_{tot} = \Sigma R_i = \int dR$$

$$\text{parallel} \Rightarrow \frac{1}{R_{tot}} = \Sigma \frac{1}{R_i} = \int \frac{1}{dR}$$

$$\Phi_B = \oint B \cdot ds$$

$$\epsilon = -\dot{\Phi}_B \text{ (Lenz's law)}$$

$$\underline{\dot{B} \neq 0, \dot{S} \neq 0, \dot{\theta} \neq 0} \Rightarrow \dot{\Phi}_B$$

$$\vec{B}_{(r)\hat{\theta}} = (I + \dot{E}) \cdot \frac{1}{r}$$

מגנטיות

נוסחאות ראשונות

$$L = \frac{\Phi}{I}$$

$$M = \frac{\Phi_1}{I_2} = \frac{\Phi_2}{I_1}$$

$$\vec{\mu} = IS\hat{n}$$

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

$$\begin{aligned} \vec{\nabla} \times \vec{E} &= \left(\frac{1}{r} \frac{\partial E_z}{\partial \theta} - \frac{\partial E_{\hat{\theta}}}{\partial z} \right) \hat{r} \\ \vec{\nabla} \times \vec{E} &= -\frac{\partial B}{\partial t} \left(\frac{\partial E_{\hat{r}}}{\partial z} - \frac{\partial E_z}{\partial r} \right) \hat{\theta} \\ &\quad \frac{1}{r} \left[\frac{\partial (r E_{\hat{\theta}})}{\partial r} - \frac{\partial E_{\hat{r}}}{\partial \theta} \right] \hat{z} \end{aligned}$$

$$\text{amper } \oint B \cdot dl = I_{in}$$

$$d\vec{B}_{\text{BioSavar}} = \frac{I}{r^2} (d\vec{l} \times \hat{r})$$

$$\vec{B}_{(r)\hat{\theta}} = I \frac{1}{r}$$

$$\vec{B}_{(0,R)\hat{z}} = \frac{I}{R} \hat{z}$$

$$\vec{B}_{(r)\hat{\theta}} = \frac{I}{R^2} r$$

$$\vec{B}_{(z,R)\hat{z}} = I \frac{R^2}{(z^2 + R^2)^{\frac{3}{2}}} \hat{z}$$

$$\vec{B}_{(n)\hat{z}} = n \cdot I$$

$$\vec{B}_{(z,R)\hat{z}} = \frac{q \cdot \omega}{\pi R^2} \left[\frac{R^2 + 2Z^2}{(R^2 + Z^2)^{\frac{3}{2}}} - 2z \right]$$

$$\vec{B}_{(y)\hat{x}} = \pm \vec{K} \hat{z}$$

$$\vec{F}_{\text{lorentz}} = q\vec{V} \times \vec{B}$$

$$\vec{F}_{\text{BIL}} = (\vec{I} \times \vec{B})L = \lambda(\vec{v} \times \vec{B})L$$

מגנטיות

שדות במצבים מיוחדים

$$\vec{I} = \frac{dQ}{dt} = Q \cdot \vec{v} = \lambda \cdot \vec{v} = Q_{\text{ring}} \cdot \vec{\omega}$$